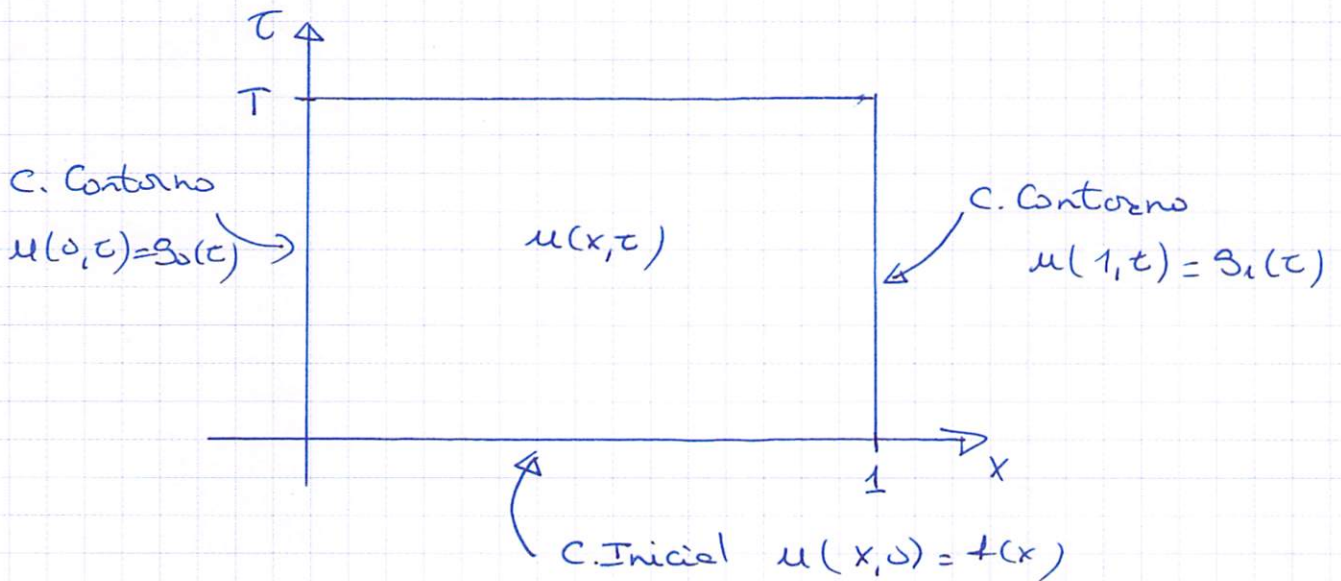


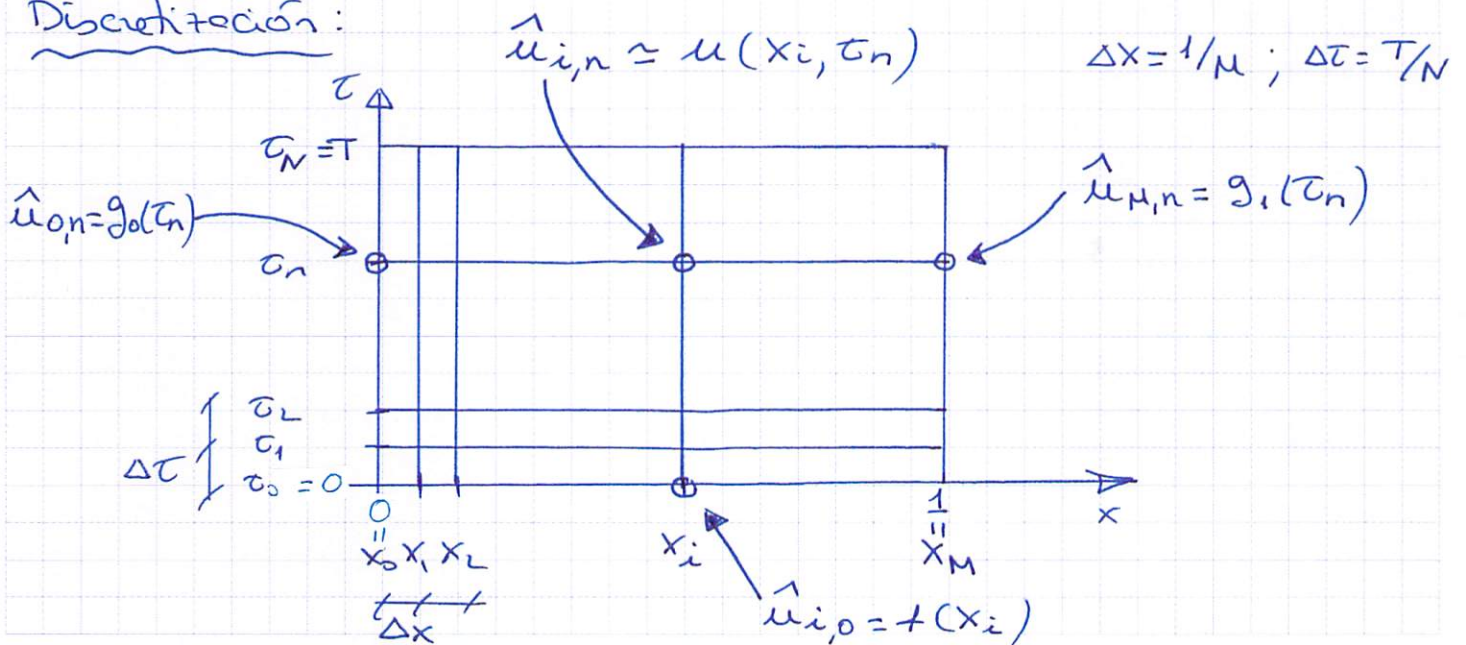
# Ecuaciones Parabólicas 1D

$$\left\{ \begin{array}{ll} u_{\tau} = u_{xx} & ; 0 < x < 1 \\ & ; 0 < \tau < T \end{array} \right. \quad (\text{EDP})$$

$$\left\{ \begin{array}{ll} u(x, 0) = f(x) & 0 \leq x \leq 1 \quad (\text{C. Inicial}) \\ u(0, \tau) = g_0(\tau) & 0 < \tau \leq T \quad (\text{C. Contorno}) \\ u(1, \tau) = g_1(\tau) & 0 < \tau \leq T \quad (\text{C. Contorno}) \end{array} \right.$$



Discretización:





## METODO EXPLICITO

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$$\left. \left[ u_t - u_{xx} \right] \right|_{\substack{x=x_i \\ t=t_n}} = 0$$

$$\left\{ \begin{array}{l} u_t \Big|_{\substack{x=x_i \\ t=t_n}} = \frac{u(x_i, t_{n+1}) - u(x_i, t_n)}{\Delta t} - u_{tt} \frac{\Delta t}{2} + \Theta(\Delta t^2) \\ u_{xx} \Big|_{\substack{x=x_i \\ t=t_n}} = \frac{u(x_{i+1}, t_n) - 2u(x_i, t_n) + u(x_{i-1}, t_n))}{\Delta x^2} - u_{xxxx} \frac{\Delta x^2}{12} + \Theta(\Delta x^4) \end{array} \right.$$

$$\frac{u(x_i, t_{n+1}) - u(x_i, t_n)}{\Delta t} - \frac{u(x_{i+1}, t_n) - 2u(x_i, t_n) + u(x_{i-1}, t_n))}{\Delta x^2} = \tau(x_i, t_n)$$

$$\tau(x_i, t_n) = \left[ u_{tt} \frac{\Delta t}{2} - u_{xxxx} \frac{\Delta x^2}{12} \right] \Big|_{\substack{x=x_i \\ t=t_n}} + \Theta(\Delta t^2) + \Theta(\Delta x^4)$$

$$\text{Se define: } \lambda = \frac{\Delta t}{\Delta x^2}$$

$$u_t = u_{xx} \Rightarrow u_{tt} = u_{xxt} = u_{txx} = (u_t)_{xx} = u_{xxxx}$$

dejo:

$$\tau(x_i, t_n) = \frac{u_{tt}}{12} \Big|_{\substack{x=x_i \\ t=t_n}} (6\lambda - 1) \Delta x^2 + \Theta(\Delta x^4 \cdot \lambda^2) + \Theta(\Delta x^4)$$

$$\left\{ \begin{array}{l} u(x_i, t_{n+1}) = \lambda u(x_{i-1}, t_n) + (1 - 2\lambda) u(x_i, t_n) + \lambda u(x_{i+1}, t_n) + \Delta t \cdot \tau(x_i, t_n) \\ \hat{u}_{i,n+1} = \lambda \hat{u}_{i-1,n} + (1 - 2\lambda) \hat{u}_{i,n} + \lambda \hat{u}_{i+1,n} \end{array} \right.$$

$$\left\{ \begin{array}{l} \hat{u}_{i,0} = u(x_i, t_0) = f(x_i) \quad ; \quad i = 0, \dots, M \\ \hat{u}_{0,n+1} = u(x_0, t_{n+1}) = g_0(t_{n+1}) \quad ; \quad n = 0, \dots, N-1 \\ \hat{u}_{M,n+1} = u(x_M, t_{n+1}) = g_1(t_{n+1}) \quad ; \quad n = 0, \dots, N-1 \end{array} \right.$$



## Convergencia

Sea:  $W_{i,n} = u(x_i, t_n) - \hat{u}_{i,n} \equiv$  error global de truncamiento

$$W_{i,n+1} = \lambda W_{i-1,n} + (1-2\lambda) W_{i,n} + \lambda W_{i+1,n} + \Delta\tau \tau(x_i, t_n)$$

$$\begin{cases} W_{i,0} = 0 & ; i = 0, \dots, M \\ W_{0,n+1} = 0 & ; n = 0, \dots, N-1 \\ W_{M,n+1} = 0 & ; n = 0, \dots, N-1 \end{cases}$$

Si  $0 < \lambda \leq 1/2 \Rightarrow 0 \leq (1-2\lambda) < 1$ , luego  $\begin{cases} \lambda \geq 0 \\ (1-2\lambda) \geq 0 \end{cases}$

Por tanto:

$$|W_{i,n+1}| \leq \lambda |W_{i-1,n}| + (1-2\lambda) |W_{i,n}| + \lambda |W_{i+1,n}| + |\Delta\tau| |\tau(x_i, t_n)|$$

Sea:  $W_{\max}(n) = \max_{\substack{1 \leq i \leq M-1 \\ 0 \leq j \leq n}} |W_{i,j}|$ ;  $\tau_{\max}(n) = \max_{\substack{1 \leq i \leq M-1 \\ 0 \leq j \leq n}} |\tau(x_i, t_n)|$

Entonces:

$$|W_{i,n+1}| \leq [\lambda + (1-2\lambda) + \lambda] W_{\max}(n) + |\Delta\tau| \tau_{\max}(n); \forall i$$

luego

$$W_{\max}(n+1) \leq W_{\max}(n) + |\Delta\tau| \tau_{\max}(n)$$

Por tanto:

$$W_{\max}(0) = 0$$

$$W_{\max}(1) \leq W_{\max}(0) + |\Delta\tau| \tau_{\max}(0)$$

$$W_{\max}(2) \leq W_{\max}(1) + |\Delta\tau| \tau_{\max}(1)$$

...

$$W_{\max}(n+1) \leq W_{\max}(n) + |\Delta\tau| \tau_{\max}(n)$$

$$\Rightarrow W_{\max}(n+1) \leq |\Delta\tau| \sum_{j=0}^n \tau_{\max}(j) \leq |\Delta\tau| (n+1) \tau_{\max}(n)$$

Y finalmente:

$$W_{\max}(n+1) \leq |\tau_{n+1} - \tau_0| \cdot \max_{\substack{1 \leq i \leq M-1 \\ 0 \leq j \leq n}} \left| \frac{(6\lambda-1)}{12} \Delta x^2 u_{ccc} \right|_{\substack{x=x_i \\ t=\tau_j}} + \Theta(\Delta x^4 + \lambda \Delta x^4)$$

$$\begin{array}{l} 0 < \lambda \leq 1/2 \Rightarrow W_{\max}(n+1) = \Theta(\Delta x^2) \\ \lambda = 1/6 \Rightarrow W_{\max}(n+1) = \Theta(\Delta x^4) \end{array} \Rightarrow \underline{\text{ES CONVERGENTE}}$$



# Análisis de Estabilidad de Von Neumann

IDEA:  $\left\{ \begin{array}{l} \text{BUSCAR SOLUCIONES TIPO } \hat{u}_{i,n} = \psi(\tau_n) e^{j\beta x_i}; j = \sqrt{-1} \\ \text{OBLIGAN A QUE } \left\{ \begin{array}{l} |\xi| \leq 1 \\ \text{con } \xi = \frac{\psi(\tau_{n+\Delta\tau})}{\psi(\tau_n)} = \text{coeficiente de amplificación} \end{array} \right. \end{array} \right.$

$$\boxed{\hat{u}_{i,n+1} = \lambda \hat{u}_{i-1,n} + (1-2\lambda) \hat{u}_{i,n} + \lambda \hat{u}_{i+1,n}}$$

$$\psi(\tau_{n+\Delta\tau}) e^{j\beta x_i} = \lambda \psi(\tau_n) e^{j\beta(x_i-\Delta x)} + (1-2\lambda) \psi(\tau_n) e^{j\beta x_i} + \lambda \psi(\tau_n) e^{j\beta(x_i+\Delta x)}$$

$$\begin{aligned} \xi = \frac{\psi(\tau_{n+\Delta\tau})}{\psi(\tau_n)} &= \lambda e^{-j\beta\Delta x} + (1-2\lambda) + \lambda e^{j\beta\Delta x} \\ &= 1 + \lambda \left[ e^{-j\beta\Delta x} + e^{j\beta\Delta x} - 2 \right] \\ &= 1 + \lambda \left[ (\cos(\beta\Delta x) - j\cancel{\sin(\beta\Delta x)}) + (\cos(\beta\Delta x) + j\cancel{\sin(\beta\Delta x)}) - 2 \right] \\ &= 1 + 2\lambda \left[ \cos(\beta\Delta x) - 1 \right] \\ &= 1 - 4\lambda \operatorname{sen}^2\left(\frac{\beta\Delta x}{2}\right) \end{aligned}$$

$$|\xi| \leq 1 \Rightarrow \left| 1 - 4\lambda \operatorname{sen}^2\left(\frac{\beta\Delta x}{2}\right) \right| \leq 1 \quad \forall \beta \Rightarrow \Delta \Rightarrow |1 - 4\lambda| \leq 1$$

$$\Rightarrow -1 \leq 1 - 4\lambda \leq 1 \Rightarrow -2 \leq -4\lambda \leq 0$$

$$\Rightarrow \left. \begin{array}{l} 0 \leq \lambda \leq 1/2 \\ \lambda = 0 \text{ no tiene sentido} \end{array} \right\} \Rightarrow$$

$$\boxed{0 < \lambda \leq 1/2}$$

CONDICIONALMENTE ESTABLE!



# MÉTODOS IMPLÍCITOS

$$\left[ u_\tau - u_{xx} \right] \Big|_{\substack{x=x_i \\ \tau=\tau_{n+1}}} = 0$$

$$\left\{ \begin{aligned} u_\tau \Big|_{\substack{x=x_i \\ \tau=\tau_{n+1}}} &= \frac{u(x_i, \tau_{n+1}) - u(x_i, \tau_n)}{\Delta \tau} + u_{\tau\tau} \frac{\Delta \tau}{2} + \Theta(\Delta \tau^2) \end{aligned} \right.$$

$$\left\{ \begin{aligned} u_{xx} \Big|_{\substack{x=x_i \\ \tau=\tau_{n+1}}} &= \frac{u(x_{i+1}, \tau_{n+1}) - 2u(x_i, \tau_{n+1}) + u(x_{i-1}, \tau_{n+1})}{\Delta x^2} - u_{xxxx} \frac{\Delta x^2}{12} + \Theta(\Delta x^4) \end{aligned} \right.$$

$$\frac{u(x_i, \tau_{n+1}) - u(x_i, \tau_n)}{\Delta \tau} - \frac{u(x_{i+1}, \tau_{n+1}) - 2u(x_i, \tau_{n+1}) + u(x_{i-1}, \tau_{n+1})}{\Delta x^2} = \tau(x_i, \tau_{n+1})$$

$$\tau(x_i, \tau_{n+1}) = \left[ -u_{\tau\tau} \frac{\Delta \tau}{2} - u_{xxxx} \frac{\Delta x^2}{12} \right] \Big|_{\substack{x=x_i \\ \tau=\tau_{n+1}}} - \Theta(\Delta \tau^2) + \Theta(\Delta x^4)$$

Se define:  $\lambda = \frac{\Delta \tau}{\Delta x^2}$

$$u_\tau = u_{xx} \Rightarrow u_{\tau\tau} = u_{xx\tau} = u_{\tau xx} = (u_\tau)_{xx} = u_{xxxx}$$

luego:

$$\tau(x_i, \tau_{n+1}) = - \frac{u_{\tau\tau}}{12} \Big|_{\substack{x=x_i \\ \tau=\tau_{n+1}}} - \frac{\Delta x^2}{12} (6\lambda + 1) + \Theta(\Delta x^4 \lambda^2) + \Theta(\Delta x^4)$$

$$-\lambda u(x_{i-1}, \tau_{n+1}) + (1 + 2\lambda) u(x_i, \tau_{n+1}) - \lambda u(x_{i+1}, \tau_{n+1}) = u(x_i, \tau_n) + \Delta \tau \tau(x_i, \tau_{n+1})$$

$$-\lambda \hat{u}_{i-1, n+1} + (1 + 2\lambda) \hat{u}_{i, n+1} - \lambda \hat{u}_{i+1, n+1} = \hat{u}_{i, n}$$

$$\left\{ \begin{aligned} \hat{u}_{i, 0} &= u(x_i, \tau_0) = f(x_i) ; i = 0, \dots, M \\ \hat{u}_{0, n+1} &= u(x_0, \tau_{n+1}) = g_0(\tau_{n+1}) ; n = 0, \dots, N-1 \\ \hat{u}_{M, n+1} &= u(x_M, \tau_{n+1}) = g_1(\tau_{n+1}) ; n = 0, \dots, N-1 \end{aligned} \right.$$



despues:

$$\begin{bmatrix} 1 & & & & & & & \\ -\lambda & (1+2\lambda) & -\lambda & & & & & \\ & -\lambda & (1+2\lambda) & -\lambda & & & & \\ & & & & & & & \\ & & & & -\lambda & (1+2\lambda) & -\lambda & \\ & & & & & & & 1 \end{bmatrix} \begin{pmatrix} \hat{u}_{0,n+1} \\ \hat{u}_{1,n+1} \\ \hat{u}_{2,n+1} \\ \vdots \\ \hat{u}_{M-1,n+1} \\ \hat{u}_{M,n+1} \end{pmatrix} = \begin{pmatrix} g_0(\tau_{n+1}) \\ \hat{u}_{1,n} \\ \hat{u}_{2,n} \\ \vdots \\ \hat{u}_{M,n} \\ g_M(\tau_{n+1}) \end{pmatrix}$$

$$y \quad \hat{u}_{i,0} = f(x_i) \quad ; \quad i = 0, \dots, M$$

//

### Análisis de Estabilidad de Von Neumann

$$\hat{u}_{i,n} = \psi(\tau_n) e^{j\beta x_i}$$

$$\boxed{-\lambda \hat{u}_{i-1,n+1} + (1+2\lambda) \hat{u}_{i,n+1} - \lambda \hat{u}_{i+1,n+1} = \hat{u}_{i,n}}$$

$$\Downarrow$$

$$-\lambda \psi(\tau_{n+1}) e^{j\beta(x_i - \Delta x)} + (1+2\lambda) \psi(\tau_{n+1}) e^{j\beta x_i} - \lambda \psi(\tau_{n+1}) e^{j\beta(x_i + \Delta x)} = \psi(\tau_n) e^{j\beta x_i}$$

$\Downarrow$

$$\xi = \frac{\psi(\tau_{n+1})}{\psi(\tau_n)} = \frac{1}{-\lambda e^{-j\beta \Delta x} + (1+2\lambda) - \lambda e^{j\beta \Delta x}} =$$

$$= \frac{1}{1 + \lambda [2 - e^{-j\beta \Delta x} - e^{j\beta \Delta x}]} = \frac{1}{1 + \lambda [2 - 2\cos \beta \Delta x]}$$

$$= \frac{1}{1 + 2\lambda (1 - \cos \beta \Delta x)} = \frac{1}{1 + 4\lambda \sin^2\left(\frac{\beta \Delta x}{2}\right)}$$

Se observa que  $\boxed{\lambda > 0} \Rightarrow \xi \leq 1 \quad \forall \beta$

¡ INCONDICIONALMENTE ESTABLE !



## MÉTODOS DE CRANK - NICOLSON

$$\left[ u_t - u_{xx} \right] \Big|_{\substack{x=x_i \\ t=\tau_n + \frac{\Delta t}{2}}} = 0$$

$$\left\{ \begin{array}{l} u_t \Big|_{\substack{x=x_i \\ t=\tau_n + \frac{\Delta t}{2}}} = \frac{u(x_i, \tau_{n+1}) - u(x_i, \tau_n)}{\Delta t} - u_{ttt} \frac{\Delta t^2}{24} + \mathcal{O}(\Delta t^4) \end{array} \right.$$

$$\left\{ \begin{array}{l} u_{xx} \Big|_{\substack{x=x_i \\ t=\tau_n + \frac{\Delta t}{2}}} = \varphi \left[ \frac{u(x_{i+1}, \tau_{n+1}) - 2u(x_i, \tau_{n+1}) + u(x_{i-1}, \tau_{n+1}))}{\Delta x^2} \right] + \\ (1-\varphi) \left[ \frac{u(x_{i+1}, \tau_n) - 2u(x_i, \tau_n) + u(x_{i-1}, \tau_n)}{\Delta x^2} \right] \end{array} \right.$$

$$- u_{xxt} \left( \frac{2\varphi-1}{2} \right) \Delta t - u_{xxxx} \frac{\Delta x^2}{12} + \mathcal{O}(\Delta t^2 + \dots)$$

$$\frac{u(x_i, \tau_{n+1}) - u(x_i, \tau_n)}{\Delta t} - \varphi \left[ \frac{u(x_{i+1}, \tau_{n+1}) - 2u(x_i, \tau_{n+1}) + u(x_{i-1}, \tau_{n+1}))}{\Delta x^2} \right] - (1-\varphi) \left[ \frac{u(x_{i+1}, \tau_n) - 2u(x_i, \tau_n) + u(x_{i-1}, \tau_n)}{\Delta x^2} \right] = \tau(x_i, \tau_n + \frac{\Delta t}{2})$$

$$\tau(x_i, \tau_n + \frac{\Delta t}{2}) = \left[ -u_{xxt} \frac{2\varphi-1}{2} \Delta t - u_{xxxx} \frac{\Delta x^2}{12} + u_{ttt} \frac{\Delta t^2}{24} \right] \Big|_{\substack{x=x_i \\ t=\tau_n + \frac{\Delta t}{2}}} + \mathcal{O}(\Delta t^2 + \dots)$$

Se define  $\lambda = \frac{\Delta t}{\Delta x^2}$

$$u_t = u_{xx} \Rightarrow \begin{cases} u_{xxt} = (u_t)_{xx} = u_{xxxx} \\ u_{ttt} = u_{xxxxx} \end{cases}$$

luego:

$$\tau(x_i, \tau_n + \frac{\Delta t}{2}) = - \left[ u_{xxxx} \frac{\Delta x^2}{12} \left( (2\varphi-1) 6\lambda + 1 \right) \right] \Big|_{\substack{x=x_i \\ t=\tau_n + \frac{\Delta t}{2}}} + \mathcal{O}(\Delta t^2 + \dots)$$

$$\left\{ \begin{array}{l} \text{CRANK-NICOLSON: } \varphi = 1/2 \Rightarrow \tau \equiv \mathcal{O}(\Delta x^2 + \Delta t^2) \\ \text{FOURTH-ORDER: } \varphi = \frac{6\lambda-1}{12\lambda} \Rightarrow \tau \equiv \mathcal{O}(\Delta x^4) \\ \lambda = \frac{1}{\sqrt{20}} \Rightarrow \tau \equiv \mathcal{O}(\Delta x^6) \end{array} \right.$$







1) HAY MÉTODOS INCONDICIONALMENTE INESTABLES

Ej: Método de Richardson

$$\left[ u_t - u_{xx} \right] \Big|_{\substack{x=x_i \\ t=\tau_n}} = 0$$

$$\begin{cases} u_t \Big|_{\substack{x=x_i \\ t=\tau_n}} = \frac{u(x_i, \tau_{n+1}) - u(x_i, \tau_{n-1})}{2\Delta\tau} + \mathcal{O}(\Delta\tau^2) \\ u_{xx} \Big|_{\substack{x=x_i \\ t=\tau_n}} = \frac{u(x_{i+1}, \tau_n) - 2u(x_i, \tau_n) + u(x_{i-1}, \tau_n))}{\Delta x^2} + \mathcal{O}(\Delta x^2) \end{cases}$$

$$\hat{u}_{i,n+1} = \hat{u}_{i,n-1} + 2\lambda \hat{u}_{i-1,n} - 4\lambda \hat{u}_{i,n} + 2\lambda \hat{u}_{i+1,n}$$

$$\hat{u}_{i,n} = \psi(\tau_n) e^{j\alpha x_i} \Rightarrow \xi - \frac{1}{\xi} = -8\lambda \alpha^2 \frac{\rho \Delta x}{2}$$

Es imposible conseguir que  $|\xi| \leq 1 \quad \forall \rho \Rightarrow$  Incondicionalmente Inestable2) HAY MÉTODOS CONDICIONALMENTE CONSISTENTES

Ej: Método de DuFort-Frankel

$$\left[ u_t - u_{xx} \right] \Big|_{\substack{x=x_i \\ t=\tau_n}} = 0$$

$$\begin{cases} u_t \Big|_{\substack{x=x_i \\ t=\tau_n}} = \frac{u(x_i, \tau_{n+1}) - u(x_i, \tau_{n-1})}{2\Delta\tau} + \mathcal{O}(\Delta\tau^2) \\ u_{xx} \Big|_{\substack{x=x_i \\ t=\tau_n}} = \frac{u(x_{i+1}, \tau_n) - u(x_i, \tau_{n+1}) - u(x_i, \tau_{n-1}) + u(x_{i-1}, \tau_n)}{\Delta x^2} \\ \quad + u_{tt} \left( \frac{\Delta\tau}{\Delta x} \right)^2 + \mathcal{O}(\Delta x^2 + \dots) \end{cases}$$

Si  $\Delta\tau = \lambda \Delta x^2$  ;  $\lambda = c\tau$  y  $\Delta x \rightarrow 0 \Rightarrow$  consistenteSi  $\Delta\tau = c \Delta x$  ;  $c = c\tau$  y  $\Delta x \rightarrow 0 \Rightarrow$  NO CONSISTENTE (\*)(\*) ES CONSISTENTE CON  $u_t - u_{xx} + c^2 u_{tt} = 0$