

PROBLEMAS ELÍPTICOS 1D

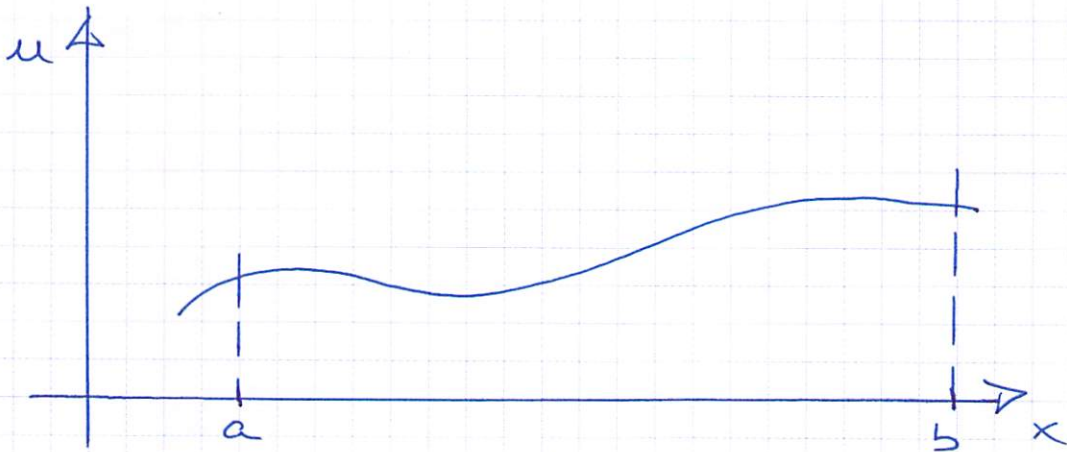
$$u_{xx} = f(x) \quad ; \quad x \in (a, b) \quad \leftarrow \text{EDP}$$

1) Condiciones de contorno tipo DIRICHLET:

$$\begin{cases} x=a \rightarrow u(x) = u_a \\ x=b \rightarrow u(x) = u_b \end{cases}$$

2) Condiciones de contorno tipo MIXTO (NEUMANN-DIRICHLET):

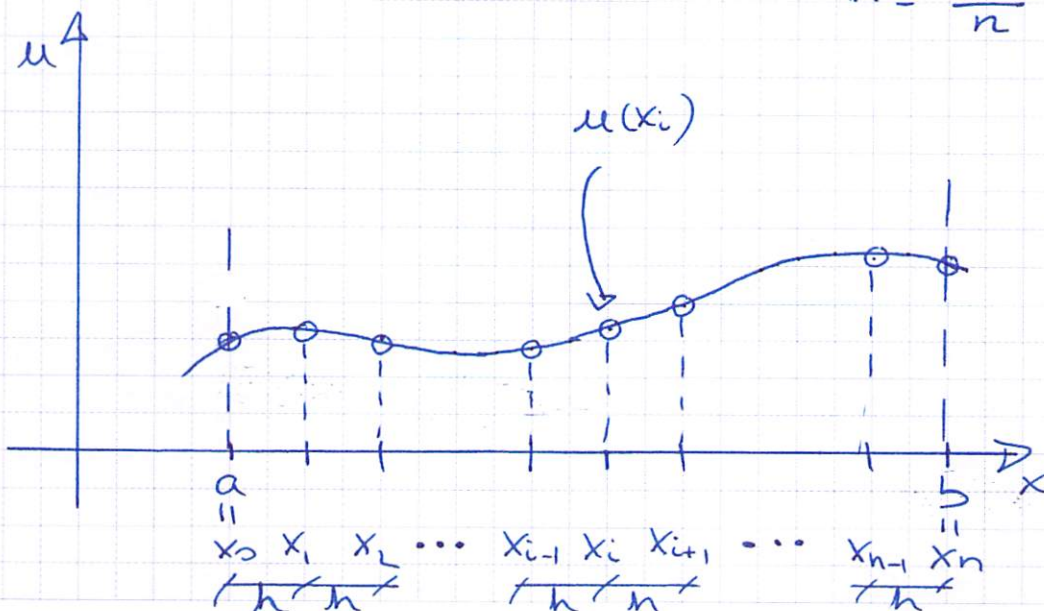
$$\begin{cases} x=a \rightarrow u_x(x) = u'_a \\ x=b \rightarrow u(x) = u_b \end{cases}$$



Discretización

$$\hat{u}_i \approx u(x_i)$$

$$h = \frac{b-a}{n}$$



1) C.C. tipo DIRICHLET

$$\{u_{xx} - \varphi(x)\}\Big|_{x=x_i} = 0 \quad ; \quad i = 1, \dots, n-1$$

$$\rightarrow u_{xx}\Big|_{x=x_i} = \frac{u(x_{i-1}) - 2u(x_i) + u(x_{i+1}))}{h^2} + \mathcal{O}(h^2)$$

 \Rightarrow

$$\left\{ \begin{array}{l} \frac{u(x_{i-1}) - 2u(x_i) + u(x_{i+1}))}{h^2} - \varphi(x_i) + \mathcal{O}(h^2) = 0 \\ \hat{u}_{i-1} - 2\hat{u}_i + \hat{u}_{i+1} - \varphi(x_i) = 0 \end{array} \right.$$

para $i = 1, \dots, n-1$

$$\text{C.C.: } \begin{cases} u(x_0) = u_a \rightarrow \hat{u}_0 = u_a \\ u(x_n) = u_b \rightarrow \hat{u}_n = u_b \end{cases}$$

 \Rightarrow

$$\begin{pmatrix} 1 & 0 & & & & & \\ 1 & -2 & 1 & & & & \\ & 1 & -2 & 1 & & & \\ & & & & & & \\ & & & & & & \\ & & & & 1 & -2 & 1 \\ & & & & & 1 & -2 & 1 \\ & & & & & & 0 & 1 \end{pmatrix} \begin{pmatrix} \hat{u}_0 \\ \hat{u}_1 \\ \hat{u}_2 \\ \vdots \\ \hat{u}_{n-2} \\ \hat{u}_{n-1} \\ \hat{u}_n \end{pmatrix} = \begin{pmatrix} u_a \\ h^2\varphi(x_1) \\ h^2\varphi(x_2) \\ \vdots \\ h^2\varphi(x_{n-2}) \\ h^2\varphi(x_{n-1}) \\ u_b \end{pmatrix}$$

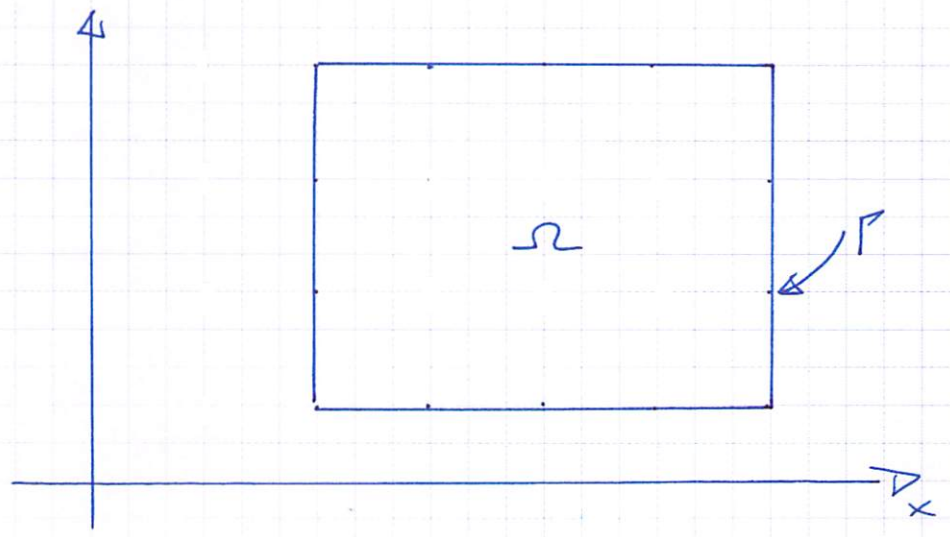
 \Leftrightarrow

$$\begin{pmatrix} -2 & 1 & & & & & \\ 1 & -2 & 1 & & & & \\ & 1 & -2 & 1 & & & \\ & & & & & & \\ & & & & & & \\ & & & & 1 & -2 & 1 \\ & & & & & 1 & -2 \end{pmatrix} \begin{pmatrix} \hat{u}_1 \\ \hat{u}_2 \\ \vdots \\ \hat{u}_{n-2} \\ \hat{u}_{n-1} \end{pmatrix} = \begin{pmatrix} h^2\varphi(x_1) - u_a \\ h^2\varphi(x_2) \\ \vdots \\ h^2\varphi(x_{n-2}) \\ h^2\varphi(x_{n-1}) - u_b \end{pmatrix}$$

Además: $\hat{u}_0 = u_a$, $\hat{u}_n = u_b$

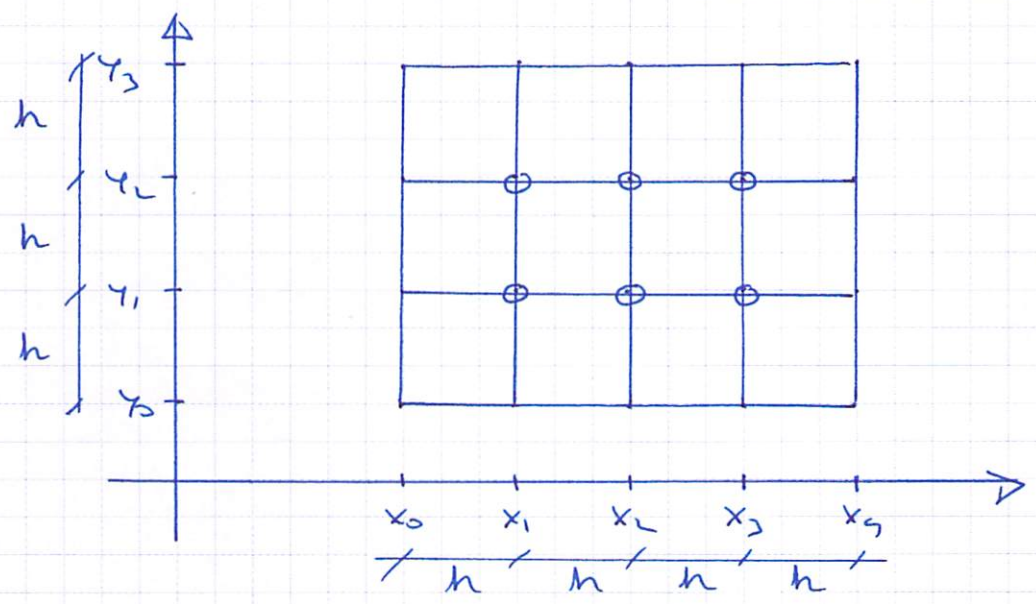
PROBLEMAS ELÍPTICOS 2D

$$E: \begin{cases} u_{xx} + u_{yy} = f(x,y) & (x,y) \in \Omega \\ u(x,y) = g(x,y) & (x,y) \in \Gamma \end{cases}$$



Discretización:

$$\hat{u}_{ij} \approx u(x_i, y_j)$$



Nota:

- En este caso $\Delta x = \Delta y = h$ (no tiene por qué ser así)

- Incógnitas $\begin{cases} \hat{u}_{12}, \hat{u}_{22}, \hat{u}_{32} \\ \hat{u}_{11}, \hat{u}_{21}, \hat{u}_{31} \end{cases}$

$$\left[(u_{xx} + u_{yy}) - \varphi(x_i, y_j) \right] \Big|_{\substack{x=x_i \\ y=y_j}} = 0 \quad ; \quad \begin{array}{l} i=1, \dots, 3 \\ j=1, 2 \end{array}$$

$$(u_{xx} + u_{yy}) \Big|_{\substack{x=x_i \\ y=y_j}} = \frac{u(x_{i-1}, y_j) - 2u(x_i, y_j) + u(x_{i+1}, y_j))}{h^2} + \mathcal{O}(h^2) \\ + \frac{u(x_i, y_{j-1}) - 2u(x_i, y_j) + u(x_i, y_{j+1}))}{h^2} + \mathcal{O}(h^2)$$

$$\Rightarrow \frac{u(x_{i-1}, y_j) + u(x_i, y_{j-1}) - 4u(x_i, y_j) + u(x_i, y_{j+1}) + u(x_{i+1}, y_j)}{h^2} - \varphi(x_i, y_j) + \mathcal{O}(h^2) = 0 \\ \hat{u}_{i-1,j} + \hat{u}_{i,j-1} - 4\hat{u}_{i,j} + \hat{u}_{i,j+1} + \hat{u}_{i+1,j} - \varphi(x_i, y_j) = 0$$

$$\text{para } \begin{cases} i=1, \dots, 3 \\ j=1, 2 \end{cases}$$

$$\text{c.c.: } u(x_i, y_j) = g(x_i, y_j) \rightarrow \hat{u}_{i,j} = g(x_i, y_j) \text{ en el contorno } \Gamma$$

$$\Rightarrow \left[\begin{array}{ccc|ccc} -4 & 1 & 0 & 1 & 0 & 0 \\ 1 & -4 & 1 & 0 & 1 & 0 \\ 0 & 1 & -4 & 0 & 0 & 1 \\ \hline 1 & 0 & 0 & -4 & 1 & 0 \\ 0 & 1 & 0 & 1 & -4 & 1 \\ 0 & 0 & 1 & 0 & 1 & -4 \end{array} \right] \begin{Bmatrix} \hat{u}_{1,2} \\ \hat{u}_{2,2} \\ \hat{u}_{3,2} \\ \hat{u}_{1,1} \\ \hat{u}_{2,1} \\ \hat{u}_{3,1} \end{Bmatrix} = \begin{Bmatrix} h^2 \varphi_{1,2} - g_{0,2} - g_{1,3} \\ h^2 \varphi_{2,2} - g_{2,3} \\ h^2 \varphi_{3,2} - g_{4,2} - g_{3,3} \\ h^2 \varphi_{1,1} - g_{0,1} - g_{1,0} \\ h^2 \varphi_{2,1} - g_{2,0} \\ h^2 \varphi_{3,1} - g_{4,1} - g_{3,0} \end{Bmatrix}$$



Matriz - Simétrica

- Diagonalmente dominante

Nota:

Al discretizar el problema 1D con c.c. tipo Dirichlet, se desprecia el error local de truncamiento $\tau_i(h^L)$ tal que:

$$u_{xx}|_{x=x_i} = \frac{u(x_{i-1}) - 2u(x_i) + u(x_{i+1}))}{h^2} + \tau_i(h^L),$$

$$\text{con } \tau_i(h^L) = \underbrace{\frac{-u_{xxxxx}|_{x=x_i}}{12} h^2}_{\Theta(h^L)} + \Theta(h^4)$$

Los errores $\Theta(h^4)$ dependen de la derivada sexta y sucesivas de $u(x)$, luego

$$u_{xxxxx} = 0 \quad \forall x \quad \Rightarrow \quad \tau_i = 0 \quad (*)$$

Por tanto, cuando la solución sea un polinomio de orden 3 o inferior el método numérico será teóricamente exacto (solo errores de redondeo).

(*) Para ser $u_{xx} = f(x)$, cuando $f'' = 0 \Leftrightarrow f(x) = P_1(x)$ el método numérico proporcionará la solución exacta (solo errores de redondeo).